

# Seeding Cracks Using a Fatigue Tester for Accelerated Gear Tooth Breaking

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## **Abstract**

This report describes fatigue-induced seeded cracks in spur gears and compares them to cracks created using a more traditional seeding method, notching. Finite element analysis (FEA) compares the effective compliance of a cracked tooth to the effective compliance of a notched tooth where the crack and the notch are of the same depth. In this analysis, cracks are propagated to the desired depth using FRANC2D and effective compliances are computed in ANSYS. A compliance-based feature for detecting cracks on the fatigue tester is described. The initiated cracks are examined using both nondestructive and destructive methods. The destructive examination reveals variability in the shape of crack surfaces.

## **Background of the Study**

Of the four dominant modes of gear tooth failure (breakage, wear, pitting, and scoring), breakage is the most catastrophic and occurs precipitously, with no advanced warning. The present study is concerned with the breakage failure mode exclusively.

The work described here is a subset of a larger empirical study conducted on high-quality spur gears to evaluate performance of vibration-based features for detecting cracks and assessing crack depths. The features, also referred to as condition indicators (CIs), are summarized by References 1 to 3.

In this larger study, the gears are first spun in a dynamometer-based fixture to obtain feature baselines. The cracks are then initiated using a fatigue tester to simulate overload conditions. Finally, the fatigue induced-cracks are propagated on the dynamometer-based fixture under different operating conditions, i.e., different levels of angular speed and torque, while the actual crack length on each gear face is measured using crack-propagation sensors. The main objective is to create well-documented, statistically significant data for monitoring cracks from inception to failure.

The complete service life of a gear has two phases: crack initiation and crack propagation (Ref. 4). A crack initiation phase is typically much longer than the subsequent crack propagation phase. In crack propagation studies, the crack initiation phase is often accelerated by introducing a notch in a gear tooth. The present article describes an alternative approach to accelerate crack initiation where higher-than-normal loads are applied on a gear tooth using a fatigue tester.

## **Finite Element Analysis (FEA) of a Cracked and a Notched Tooth**

Before proceeding with accelerated crack initiation on a fatigue tester, it was of interest to compare the geometry of cracked and notched gear teeth. A gear with a notch was compared to a gear with a crack of the same length as the notch using FEA. The gear geometry was generated using a toolkit implemented in MATLAB for spur gear drawing and analysis, as shown in Figure 1. The first version of the software was created by Reference 5 and implemented by the Army Research Laboratory and NASA in Fortran. The present version is implemented by RIT, with added capabilities that include mesh generation and import and

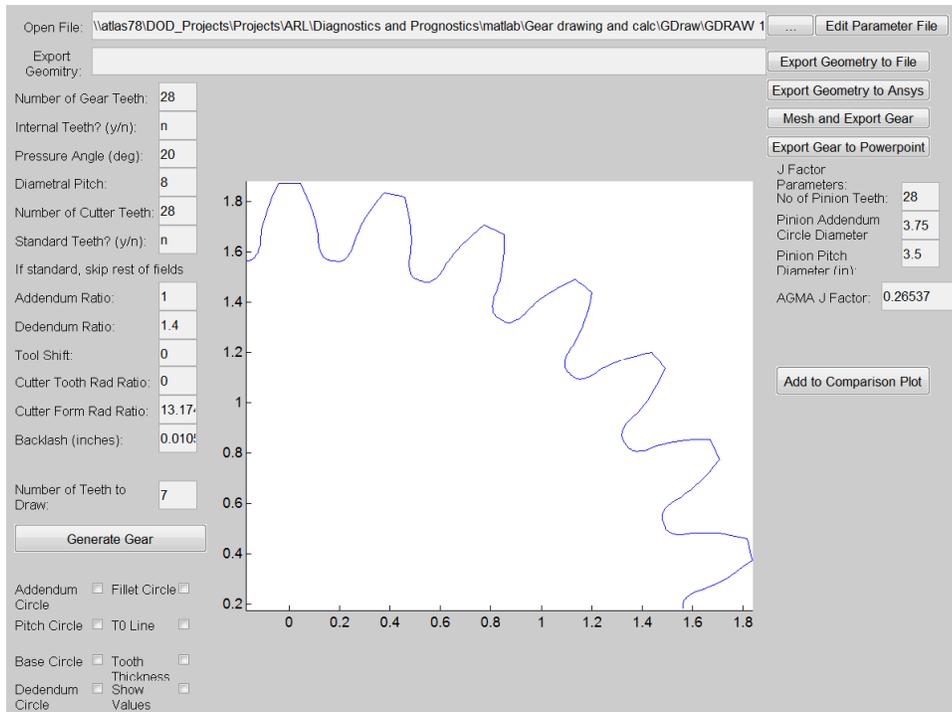


Figure 1.—Spur gear geometry generation.

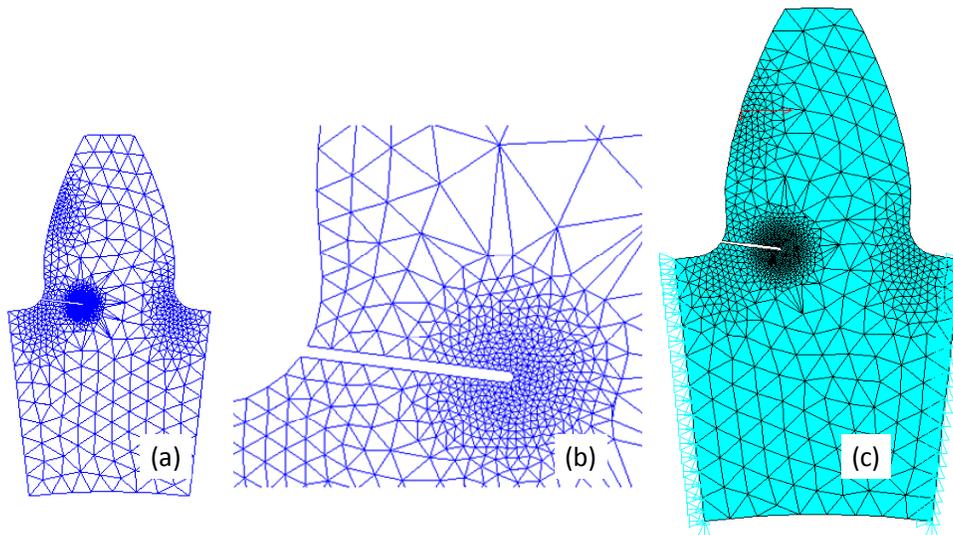


Figure 2.—A notched tooth generation within the MATLAB-based toolkit. (a) Entire tooth geometry using MATLAB. (b) Zoom into crack using MATLAB. (c) Notch exported into ANSYS.

export capabilities. The toolkit is capable of generating the gear tooth geometry, creating a finite element mesh using linear triangular elements, and exporting the meshed geometry to two commercially available finite element programs, FRANC2D and ANSYS. The mesh generator employs the *distmesh* algorithm and implementation (Ref. 6). The implementation is tailored to generate finer mesh near the application of force and high stress areas. Figure 2 shows the meshed geometry of a notched tooth, with nonuniform mesh density, generated entirely within the toolkit. The generation of the cracked tooth is a bit more involved. The uncracked tooth geometry is generated in the MATLAB toolkit. The geometry is then exported to FRANC2D, a program for simulation of crack growth (Ref. 7) where the initial crack was formed and propagated to the desired length. The cracked geometry is then read and exported to ANSYS via the MATLAB toolkit.

Figure 3 shows ANSYS static analysis of a gear with a notch, and a gear with a crack. The view is zoomed into the area of notch/crack. To minimize the difference in the crack length and the notch length, we generated the cracked geometry first, and then generated the notch later by aligning the tip of the notch to the tip of the crack.

In the first analysis, a static force of 1000 lb was applied at the gear pitch radius, normal to the surface, and the magnitude of the displacement was measured at the tip of the outer radius, as depicted in Figure 4(a). The simulation was repeated for two crack/notch lengths:  $\approx 1/8$  of the total gear thickness and  $\approx 1/4$  of the total gear thickness. Two notch sizes were studied. One for a notch radius of  $R = 0.001$  in., and the other for a notch radius of  $R = 0.002$  in. The effect of mesh density on the result for the cracked tooth was also considered. Although we computed displacements, the results can be expressed also as effective compliances, since the force is held constant.

The FEA results are summarized in Table 1 and Figure 4(b). For the crack/notch length of  $1/8$  of the gear thickness all the displacements are virtually indistinguishable, they are within less than 0.2 percent of the mean. For a crack/notch length equal to  $1/4$  of gear thickness, the notched gear exhibits larger displacements.

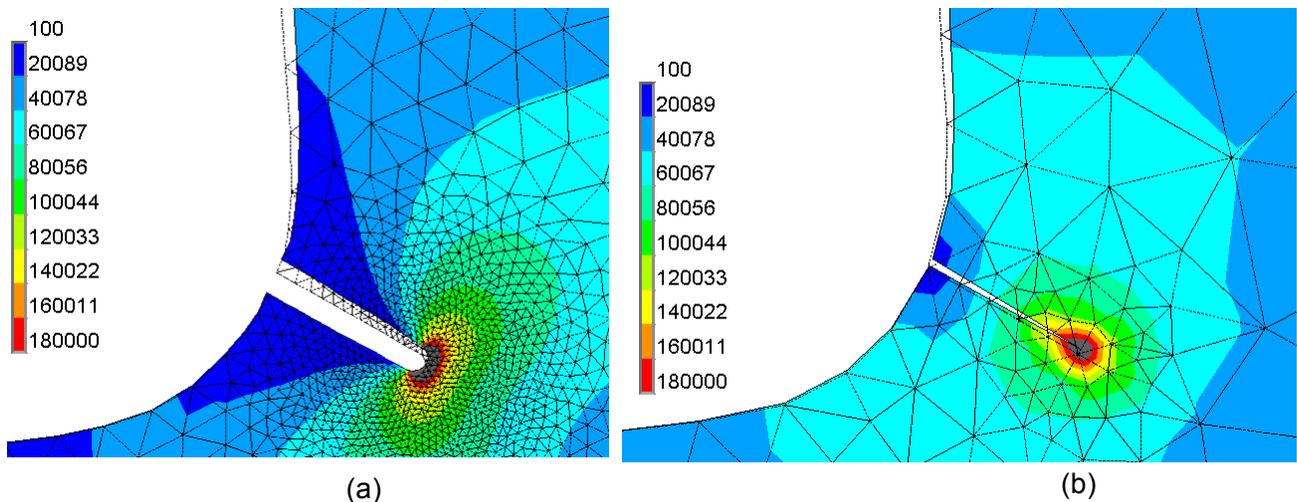


Figure 3.—Exaggerated deformations and contours of equivalent stress (psi). (a) Notch. (b) Crack.

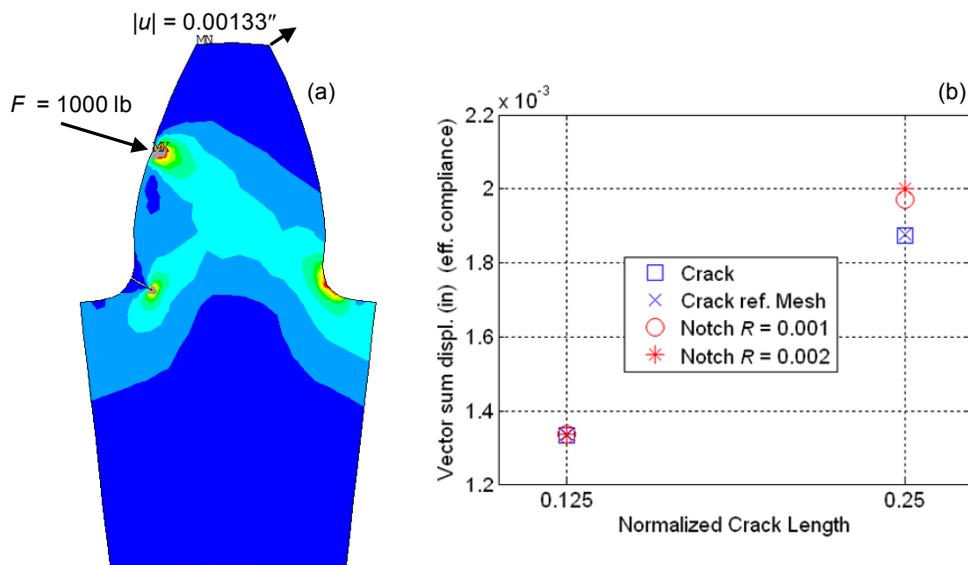


Figure 4.—Static analysis. (a) Annotated contours of equivalent stress. (b) Plot summary of displacements versus crack length.

TABLE 1.—FEM DISPLACEMENTS (in.) OF CRACKED AND NOTCHED GEAR TEETH

Normalized crack length	Crack		Notch	
	Regular mesh	Refined mesh	R = 0.001 in.	R = 0.002 in.
0.125	1.33420E-03	1.33530E-03	1.33620E-03	1.33660E-03
0.25	1.87280E-03	1.87740E-03	1.97050E-03	2.00100E-03

TABLE 2.—FUNDAMENTAL FREQUENCY (Hz) OF NOTCHED AND CRACKED GEAR TEETH

Normalized crack length	Crack		Notch	
	Regular mesh	Refined mesh	R = 0.001 in.	R = 0.002 in.
0.125	3.02100E+03	3.02100E+03	3.00200E+03	2.98900E+03
0.25	2.56700E+03	2.56300E+03	2.54500E+03	2.52400E+03

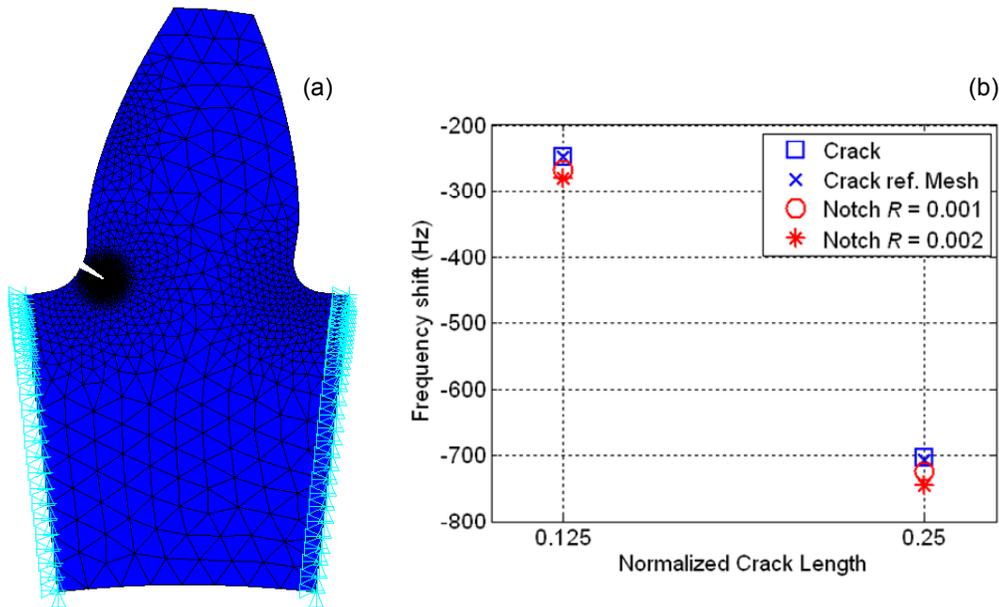


Figure 5.—Modal analysis. (a) Fundamental mode shape. (b) Summary of fundamental frequencies.

An alternative metric for comparison of cracked and notched teeth is the fundamental natural frequency of a gear tooth. Figure 5(a) shows the fundamental mode shape of the gear section of interest associated with the fundamental natural frequency. The fixed boundary conditions are indicated.

Table 2 and Figure 5(b) summarize the FEA results of the modal analysis. Table 2 shows the actual frequencies, while Figure 5(b) shows the frequency shifts from the baseline case, where the baseline is a healthy gear. The frequency decreases as the crack/notch grows. The notches give rise to the larger shifts, but the difference between the notched and cracked teeth is small.

Overall, the analysis shows that a crack and notch of the same length agree very well. Although by a small amount, notched gears exhibit more change in effective compliance and frequency shifts than their cracked counterparts. Thus, it is expected that a vibration feature is slightly more sensitive to the notched tooth than to the cracked tooth.

## Crack Initiation Fixture and Crack Initiation Process

The cracks were initiated on a commercially available fatigue tester. A special fixture, shown in Figure 6, was designed, developed, and built for this purpose. The fixture captures a single gear between two steel plates and uses an anvil to assert a load on to a single tooth. The gray anvil holder, shown in Figure 6(a), is inserted into the machine's lower ram and secured using a pin. The anvil is held within the anvil holder and captured with two set screws. The anvil width is greater than the gear tooth width and the anvil material is made of tool steel for strength. The anvil gear tooth interface is  $5^\circ$  with respect to horizontal, similar to the ASME J1619 single tooth fatigue test fixture (Ref. 8). To provide the contact area near the high point of single tooth contact (HPSTC), the centerline of the gear tooth under test is located at  $15.4^\circ$  with respect to the ground; see Figure 6(c). The gear is located between the 1 in. thick steel plates with a 1.181 in. diameter shaft locating the center of the gear. Keys were used to position the gear teeth with respect to polar angle. The primary device to react the input torque to the gear, however, was three internal gear teeth, shown in brown below, and three fasteners to provide clamping friction. Interfacing with several points within the fixture to transfer the input torque to the machine prevented damage to gear teeth not under test. The two side plates were fastened together and then bolted to a bottom subplate. This subplate was threaded and welded to a connecting rod, shown in red that threaded into the load cell on the fatigue tester.

The fatigue tester operated in load control mode with a cyclic compressive load between 100 and 3100 lb applied at a rate of 10 Hz. The crack initiation region (tooth root) was always held in tension during the test.

A compliance-based feature was developed for early detection of cracks, since the displacement-based feature did not have sufficient resolution. The crack detection is based on observation of  $N$  estimations of the feature. We compute the described feature in  $N$  points. The first  $N-M$  points are used to establish the baseline distribution of the feature, and the last  $M$  points are used for determining if the crack occurred. The crack detection is then based on the likelihood ratio as follows

$$\Lambda = \prod_{k=N-M+1}^N \frac{\Pr[c_k | H_1]}{\Pr[c_k | H_0]} \quad (1)$$

where  $H_0$  is the null hypothesis that states that there is no crack, i.e., the feature is distributed according to the distribution of a healthy gear

$$H_0 : c_k \sim \mathcal{N}(\mu_c, \sigma_c) \quad (2)$$

$\mu_c$  and  $\sigma_c$  are sample mean and standard deviation of the feature, excluding the last  $M$  points.

$$\mu_c = \frac{1}{N-M} \sum_{k=1}^{N-M} c_k \quad (3)$$

$$\sigma_c = \frac{1}{N-M-1} \sum_{k=1}^{N-M} (c_k - \mu_c)^2 \quad (4)$$

The alternative hypothesis states that the crack has occurred, that is, the feature  $c_k$  does not belong to the baseline distribution, but to a normal distribution centered around threshold  $\theta$

$$H_1 : c_k \sim \mathcal{N}(\theta, \sigma_c) \quad (5)$$

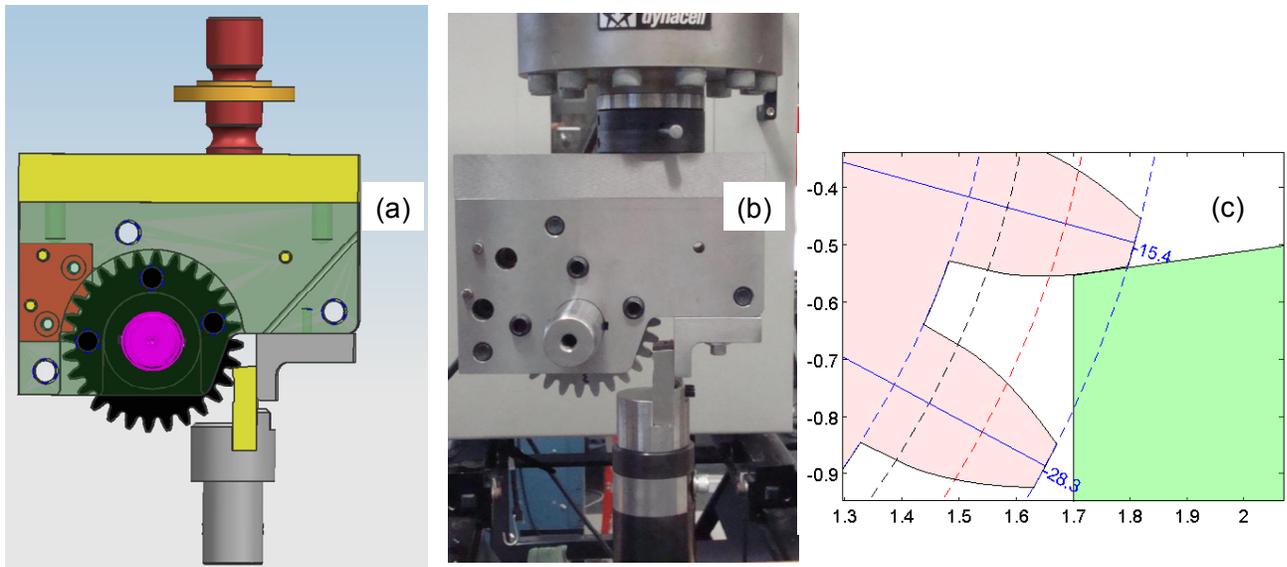


Figure 6.—The fixture for crack initiation. (a) Computer aided design image. (b) Photograph of the built fixture. (c) Anvil angle detail.

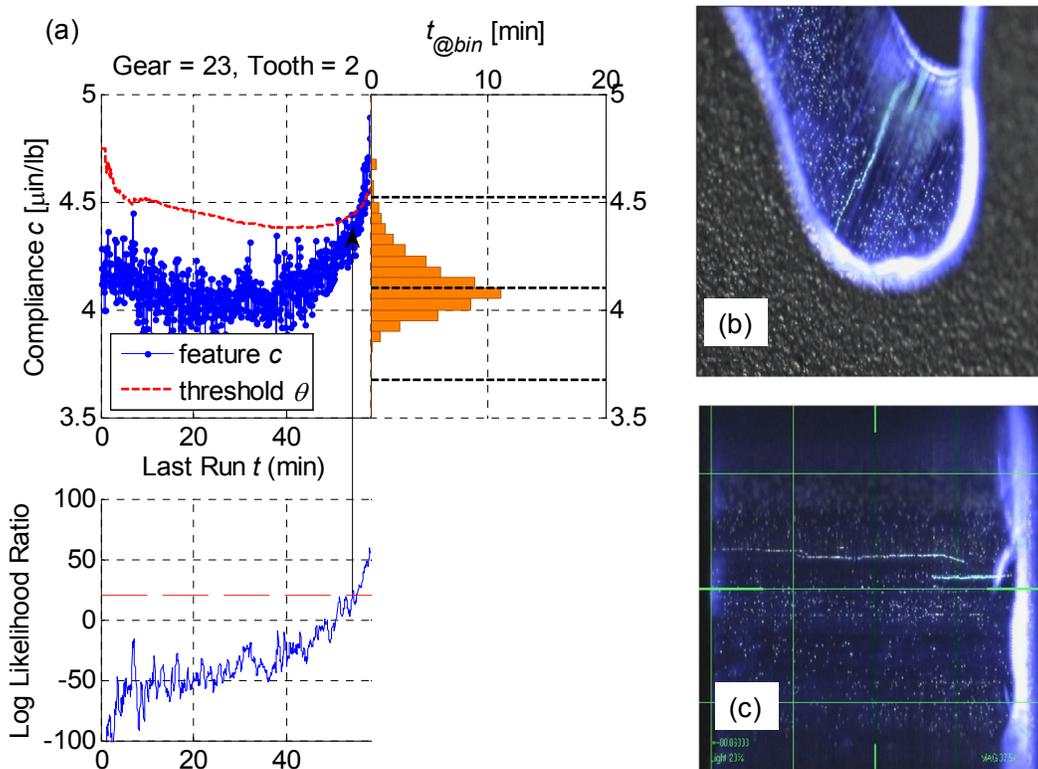


Figure 7.—Crack detection process. (a) Characteristic signals. (b) Angled view of a cracked tooth. (c) 90° view of a cracked tooth.

Figure 7 depicts the process of crack detection. The compliance feature and the threshold are shown, as well as the distribution of the compliance feature. The threshold is set initially at a conservative, empirically determined, relatively high value. As more data becomes available, the threshold is adjusted to become a certain Mahalanobis distance from the distribution mean. The distance equals to  $2.5 \sigma_c$  for the example shown in Figure 7(a).

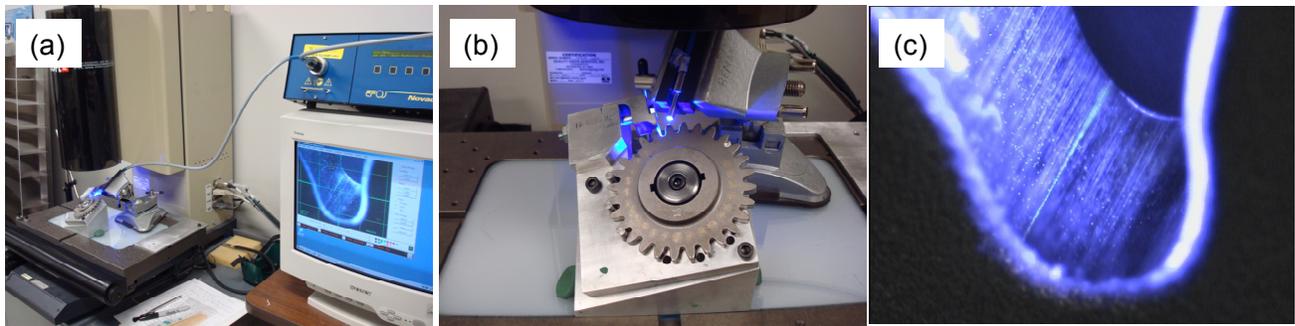


Figure 8.—Nondestructive method for crack verification. (a) Imaging system. (b) Custom gear fixture. (c) Imaged tooth.

## Crack Verification Using Nondestructive Methods

The nondestructive crack verification is based on the images taken using a commercially available high-resolution, optical video measuring system and custom fixture shown in Figure 8. The custom fixture was designed and built to place the test tooth in approximately 500 lb tension. Before the gear is placed in the fixture, the tooth under inspection is covered with a layer of fluorescent iron powder. The tooth is then placed in a strong magnetic field and observed under ultraviolet (UV) light. At a crack, the magnetic lines are disturbed. The magnetic-particle-based inspection method is a standard technique for crack detection and it is described in fracture mechanics textbooks, e.g., (Ref. 9). Glowing particles indicate fracture site.

Figure 8 illustrates the nondestructive measurement process. Prior to imaging the tooth had been subjected to approximately 29 thousand cycles of load in the 100 to 3100 lb range. The final resulting threshold for the compliance feature was  $4.40 \mu\text{in./lb}$ . The tooth was imaged  $37.5\times$  magnification.

This nondestructive method was not completely successful in detecting gear tooth cracks. The gear face area was the only region where cracks could be observed. The gear flank surface was considerable rougher. Even after polishing, no cracks were detected on the gear flanks.

## Crack Characterization Using Destructive Methods

The nondestructive inspection method was useful for confirmation of the crack initiation, but did not allow crack characterization, that is, determination of the actual crack depths. Two methods are described for measuring crack depth and characterization of the fracture surface: slicing and polishing (Method 1) and abruptly breaking teeth off after the initiation (Method 2). Figure 9 illustrates both methods. Cracks were initiated on several different teeth then inspected using both methods. The teeth in the top of Figure 9 were inspected using Method 1 and the three teeth in lower left corner were subjected to the ramped load on the fatigue tester until they fractured based on Method 2.

Method 1 employed a wire EDM to first section a number of previously tested teeth from the gear. The sectioned teeth were then sliced perpendicularly to the initial cut. The slices were polished, etched with an alcohol/nitric acid solution, and imaged with a standard metallographic microscope. Figure 10 shows the gear slices as well as images of polished sections of a tooth demonstrating crack length differences throughout the tooth thickness. The depth of gear tooth crack propagation was 1 to 1.5 mm in this example.

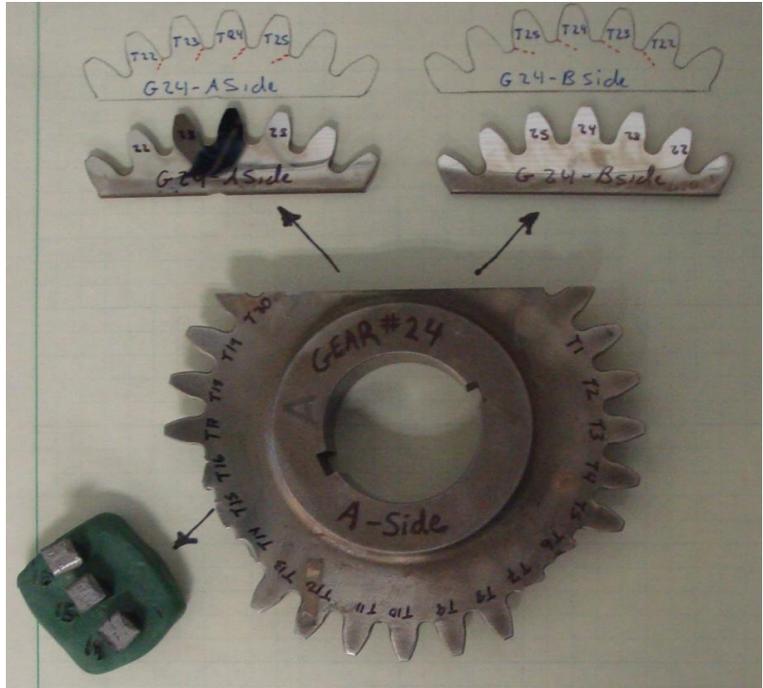


Figure 9.—Destructive inspection of gear tooth cracks.

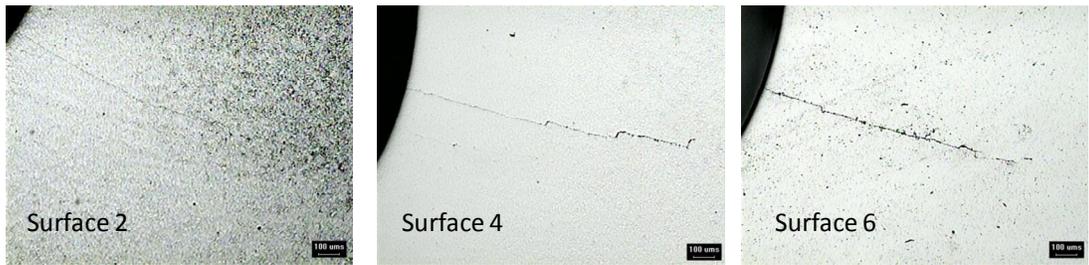
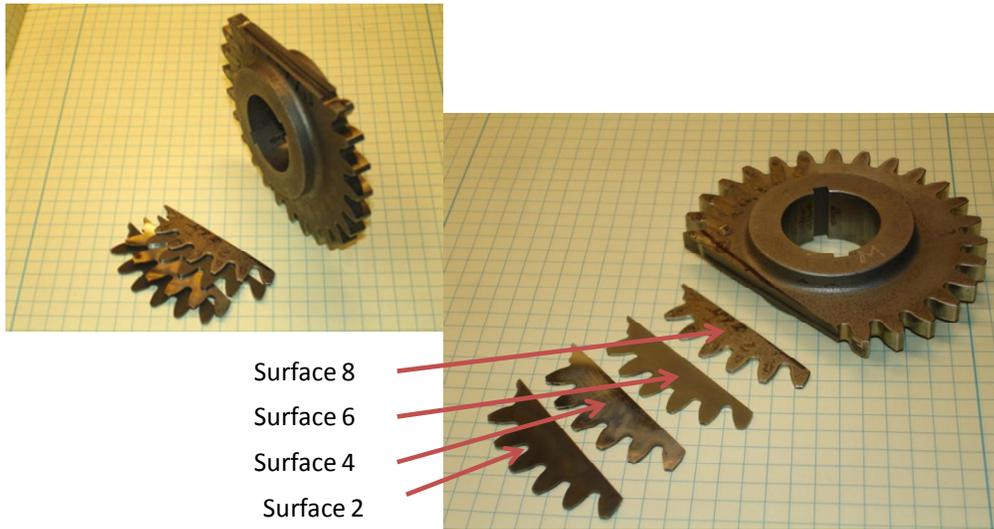


Figure 10.—Destructive inspection using Method 1.

Method 2 was relatively straight forward. After crack initiation, the test tooth was imaged with the fluorescent iron powder, returned to the fatigue fixture, and the static load increased until fracture resulted. The fracture surfaces were then imaged with a stereo microscope at 24 and 66× magnification. Figure 11 shows crack surfaces of four different teeth (all teeth imaged from the bottom). There is a clear, discernable boundary that separates the smooth surface of crack initiation from the rough surface of the abrupt breakage (see the annotation in Figure 11(b)). For the various gear tests, the crack depths in the middle of the tooth were consistent with imaging obtained using Method 1 and shown in Figure 10. However for some tests, the crack depths were virtually zero near the gear faces. It was clear that the crack profiles for these cases were significantly different than surfaces produced by notching, which have a uniform depth across the thickness of the gear. We have observed that generally as cracks propagate, the crack depth becomes more uniform across the gear thickness. Thus, for deeper cracks it is reasonable that the crack surface approaches an expected notch surface. This finding also suggests that the compliance change used for crack initiation detection as previously described will be different for notched teeth as compared to cracked teeth when the crack/notch depth is small. Method 2 was considerably more effective, far less labor intensive, and provided an immediate view of the entire crack surface as compared to Method 1. Method 1, in addition to being more laborious and requiring interpolation to visualize entire crack surface, suffered from a fundamental drawback. The wire EDM process affected crack propagation to an unknown and difficult to quantify degree. The advantage of Method 2 was that it was able to show details of the crack shape in the direction of the propagation, as shown in Figure 10.

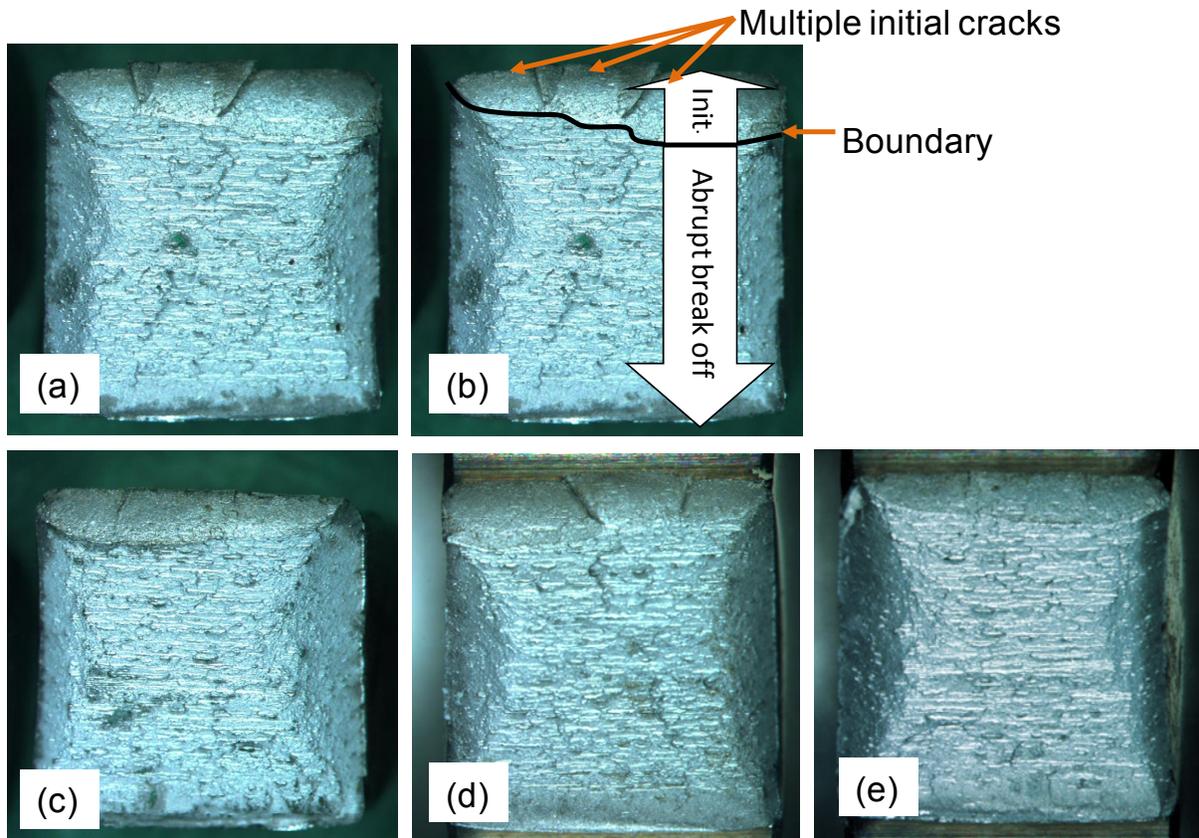


Figure 11.—Destructive inspection using Method 2.

## Summary

This paper describes an accelerated crack initiation where a selected tooth is subjected to cyclic bending on a fatigue tester. This method of seeding cracks is related to the traditional method (notching) using FEA. FEA compares effective compliance and change in fundamental natural frequencies between a cracked gear tooth and a notched gear tooth, where the notch and the crack are of the same length and of uniform depth. Both metrics consistently show that their dependence on the length of the crack/notch is considerably higher than the dependence on the type of damage. The analysis suggests a plausible conclusion that a cracked and a notched tooth will exhibit very similar vibration features for a given length of crack/notch.

The fixture for crack initiation and the associated process are described, including a compliance-based feature for crack detection. The induced cracks were verified using a nondestructive methods and characterized using the destructive methods. While the nondestructive methods indicate minimal damage to the tooth, closer (destructive) inspections show that the crack surface is somewhat irregular initially and that the maximum depth of crack propagation can be appreciable at the point of detection by the suggested feature.

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